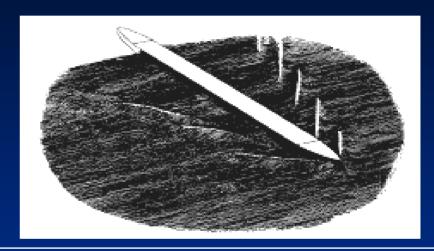
DEVELOPMENT OF A UNIFIED DESCRIPTION OF SHIP-GENERATED WAVES

(and some other recent work)

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 - Senior Engineer

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 Service Center
- Carolyn Judge
 - Post-Doctoral ResearcherUS Naval Academy



Outline of **Presentation**

- Ship Generated Wave Height
- Ship Squat in Shallow Water
- Mooring Loads from Passing Vessels

Objectives Ship-Generated Wave Heights

- Develop empirical equation to predict maximum ship-generated wave heights
 - For large displacement hulls, no fast ferries or planing craft
- Improve upon existing predictive equations:
 - Gates and Herbich (1975)
 - Sorensen and Weggel (1984) & Weggel and Sorensen (1986)
 - PIANC (1987)
- Use existing data published in the literature
 - Seek to "unify" data from various sources
- Run new lab tests to supplement existing data
 - Tests conducted in Naval Academy towing tanks

Background

Some Ship-Generated Wave Height Data in the Literature:

- "Wake Wash" of Fast Ferries

 Kofoed-Hansen and Kirkegaard (1996), Kofoed-Hansen and Mikkelsen (1997), Danish maritime Agency (1997), Kirkegaard et al (1998), Kofoed-Hansen et al (1999), Gadd (1999), Stumbo et al (1998, 1999), Whittaker et al (1999, 2000), Leer-Anderson et al. (2000), UK Maritime and Coastguard Agency (2001)

Waves Generated by Recreational Boats

 Zabawa and Ostrom (1980), Bhowmik (1975), Bhowmik et al (1982, 1991, 1992), Bhowmik and Soong (1992), Sorensen (1997)

Deep-Draft Commercial Ships



Johnson (1958, 1968), Biddie (1968), Brebner et al. (1966),
 Carruthers (1966), Das (1969), Hay (1967, 1968), Helwig (1966),
 Gates and Herbich (1977), Sorensen (1966, 1966, 1967, 1968,
 1973, 1986, 1997), Sorensen and Weggel (1984), (Kurata and Oda (1984), Weggel and Sorensen (1986), PIANC (1987)

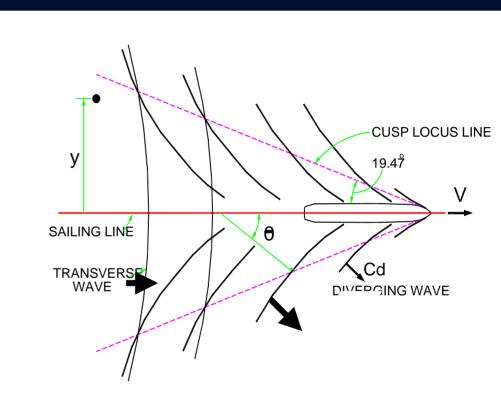
Definitions

Two wave systems:

- Diverging Waves
 - Move at angle θ relative to ship
- Transverse Waves
 - Move in same direction as ship

Maximum wave heights

- Form along "Cusp where transverse diverging waves meet
- Vary with distance from sailing line, y



FOR DEEP WATER

(after Sorensen, 1997)

Sample Wave Records

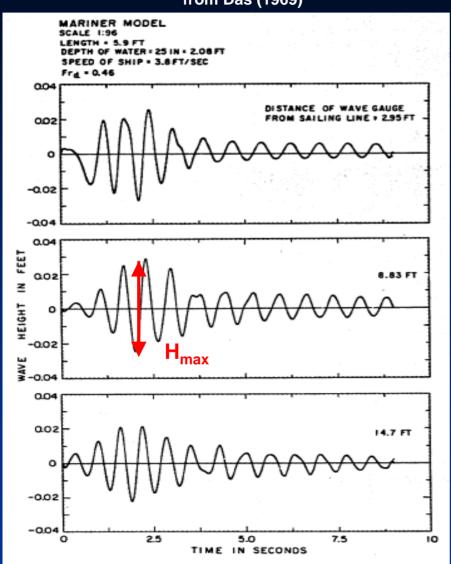
from Literature

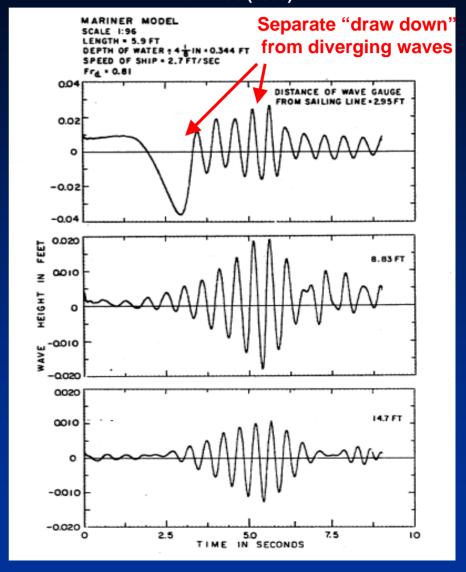
Deep Water

Shallow Water

from Das (1969)

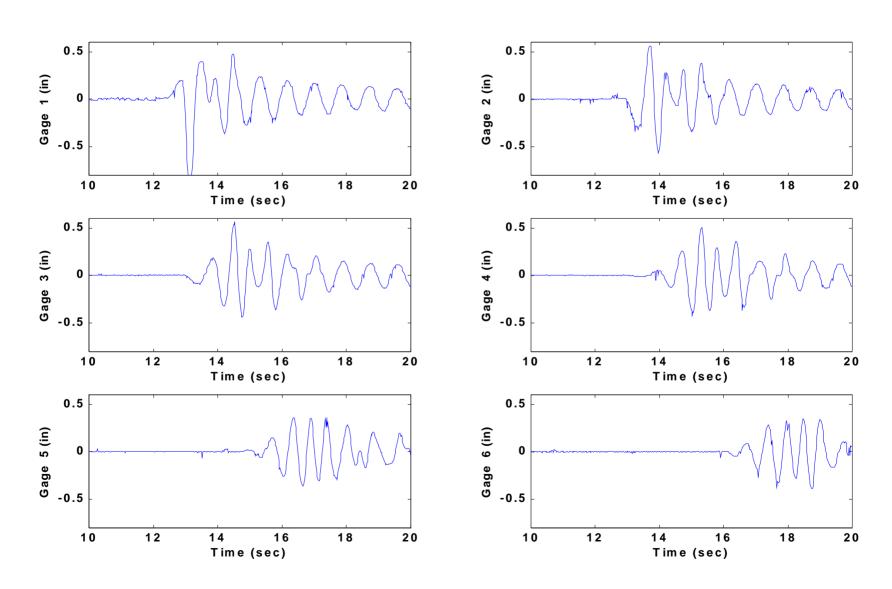
from Das (1969)



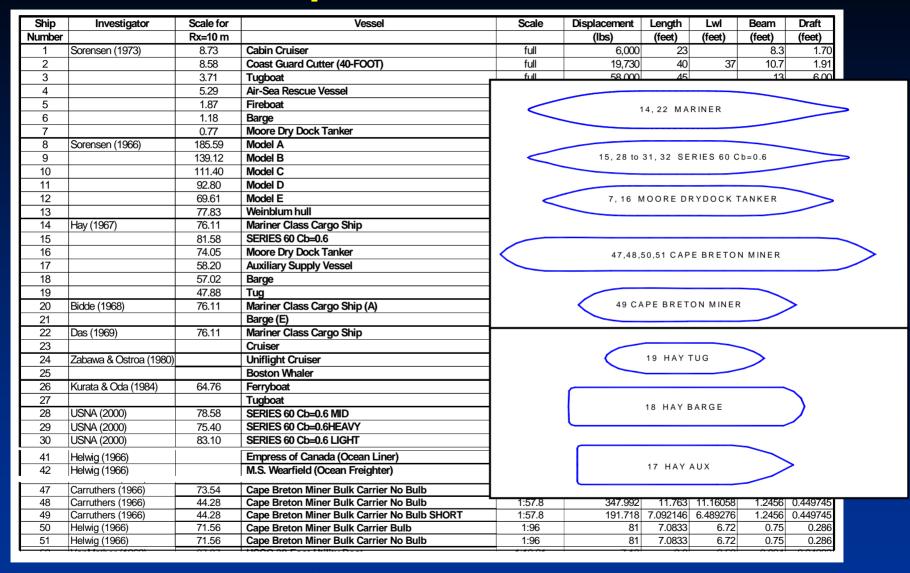


Examples from Naval Academy Tests

Waves measured at 6 distances y off sailing line



Ship Wave Database

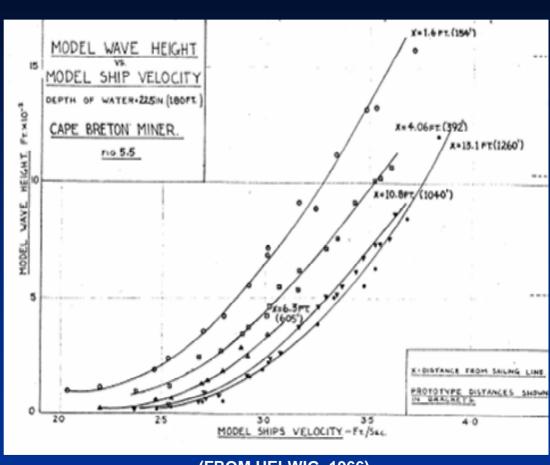


Ship wave data used in present analysis: 2100 data points for 12 ships

Sample Wave Data

from Literature

- Wave heights given in:
 - Tabular form
 - Graphical form
- Wave Heights, H, vary with:
 - Ship speed, V
 - Distance from sailing line, y
 - Water depth, d
 - Hull form



(FROM HELWIG, 1966)

Analysis of Wave Heights

- Wave height normalized by velocity head gH/V²
- Distance from sailing line can be normalized in many ways (with length scales L, B, etc) ...we use:

y/L

 Data in shallow water organized by depth-todraft ratio

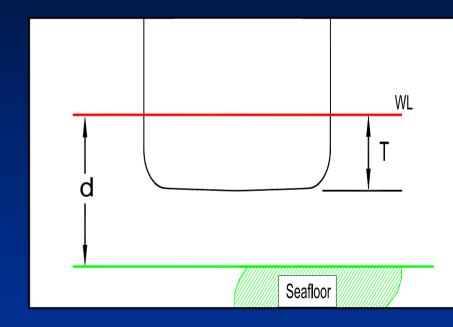
d/T

Velocities normalized as Froude Number

$$F_d = V/(gd)^{1/2}$$
 or $F_I = V/(gL)^{1/2}$

Depth-to-Draft Ratio

- Wave heights strongly affected by depth-todraft ratio, d/T
- No strong interaction
 with bottom if d/T > 3 to
- Typical commercial ships in navigation channels have d/T of 1.05 to 2
- Most wave data in literature for d/T from 1.4 to 3



Which Froude Number to Use?

Length-Based Froude Number

- Used in deep water
- Critical value F_L=0.4
 - "Hull Speed" where transverse wavelength equals ship length

Depth-Based Froude Number

- Used in shallow water
- Critical value of F_d~1.00
 - ship speed exceeds shallow water wave speed

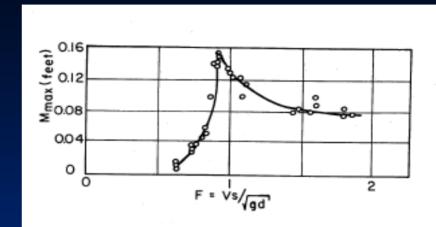


FIG. 7 MAX. WAVE HEIGHT AS A FUNCTION OF FROUDE NUMBER FOR A TYPICAL SHIP MODEL (JOHNSON, 1958)

$$F_L = \frac{V}{\sqrt{gL_s}}$$
 where $L_S = \text{ship length}$

or

$$F_d = \frac{V}{\sqrt{gd}}$$
 where $d = \text{water depth}$

Empirical Model Variation of *H* **with Distance from Sailing Line**

Havelock (1908) theory for deep water:

$$H \sim y^{-1/3}$$
 for diverging waves $H \sim y^{-1/2}$ for transverse waves

Empirical evidence in literature shows

$$H \sim y^{-0.25}$$
 to $H \sim y^{-0.6}$

- Present study:
 - Least-squares fit of both -1/3 and -1/2 models to data
 - Best-fit obtained with -1/3 power as

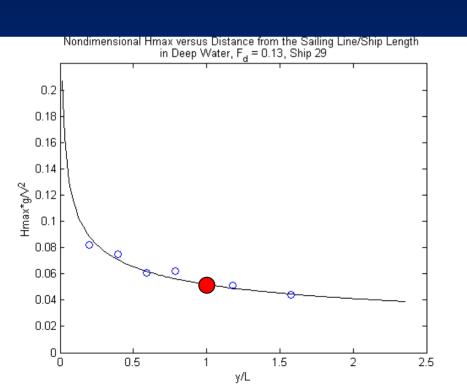
$$\frac{gH}{V^2} = C\left(\frac{y}{L}\right)^{-1/3}$$

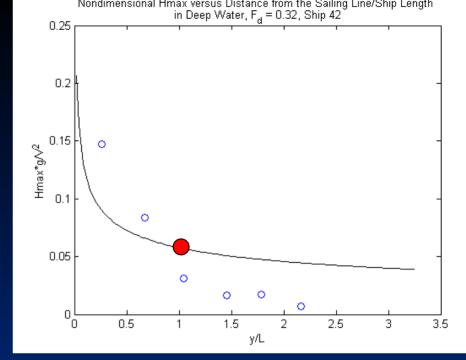
C varies with ship hull form, T/d, F_d or F_L

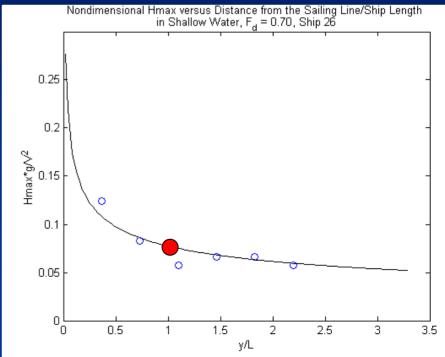
Examples of Fit

 gH/V^2 versus $(y/L)^{-1/3}$

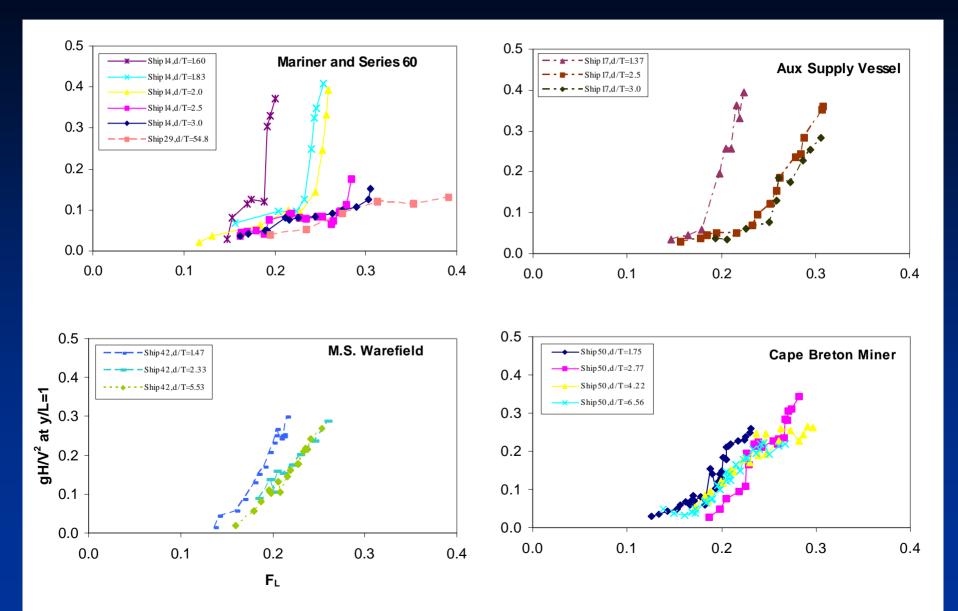
Value of gH/V^2 at y/L=1 used as a characteristic value for further analysis



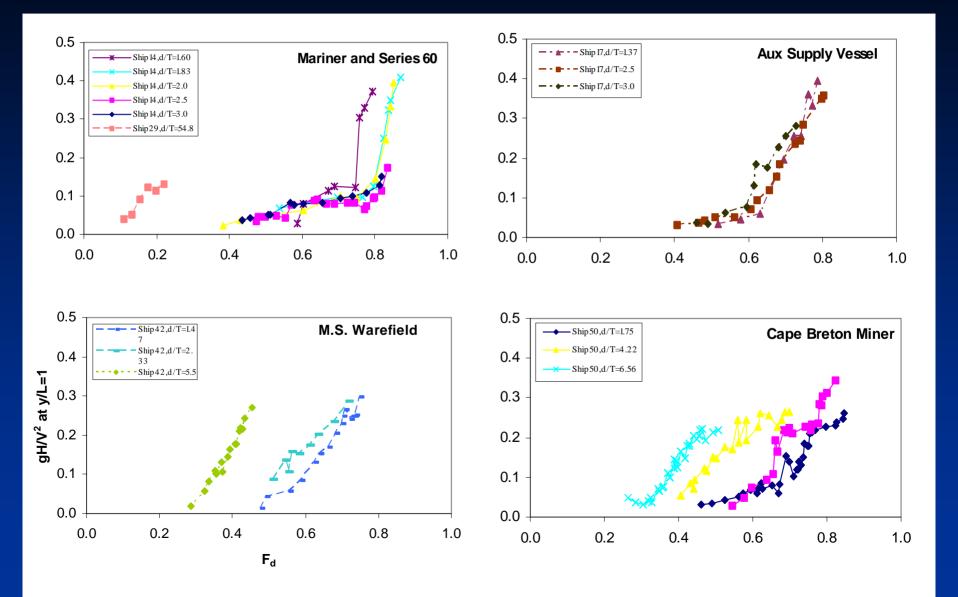




gH/V² (at y/L=1) Plotted vs Length Froude Number F_L



gH/V² (at y/L=1) Plotted vs Depth Froude Number F_d



Is there some "Modified Froude Number" which will Unify Data?

F_L works in deep water, not shallow

F_d works in shallow water, not in deep

Is there a combination that works across all water depths?

Can we "collapse" data for a given ship to a single curve?

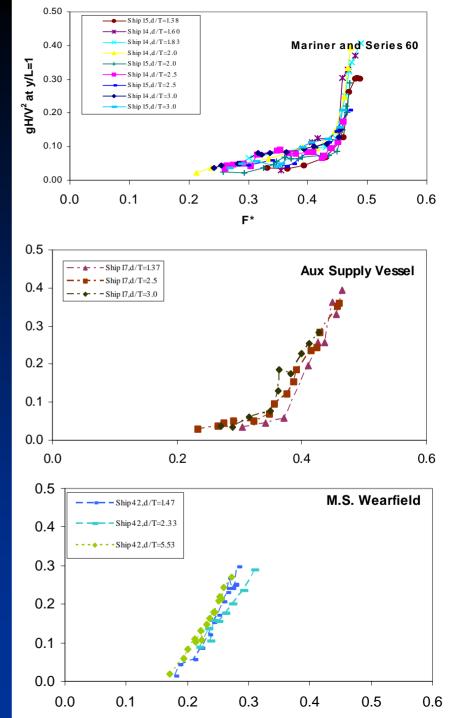
Modified Froude Number, F*

After much trial and error...

Results for each ship collapsed to single curve when plotted against:

$$F_* = F_L \exp\left(\alpha \frac{T}{d}\right)$$

Single empirical coefficient α is dependent on hull form

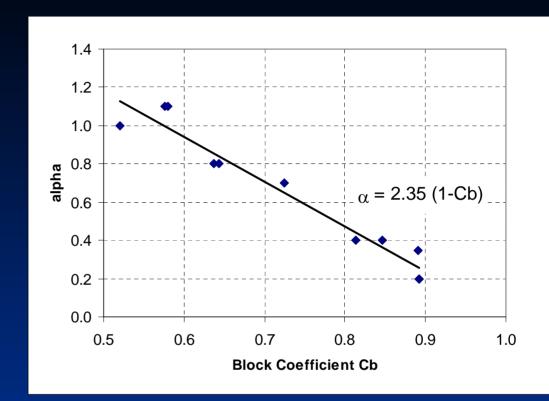


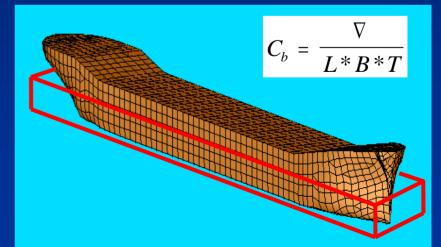
Variation of α with Hull Form

- Investigated dependence of α on hull form
- Seems to depend mainly on Block Coefficient

$$F_* = F_L \exp\left(\alpha \frac{T}{d}\right)$$
with
$$\alpha = 2.35(1 - C_b)$$

- General trends:
 - Streamlined hulls have α of 1 or more
 - Blunt hulls have α of 0.2 to 0.4





Now...Search for Relationship between gH/V² and F_{*}

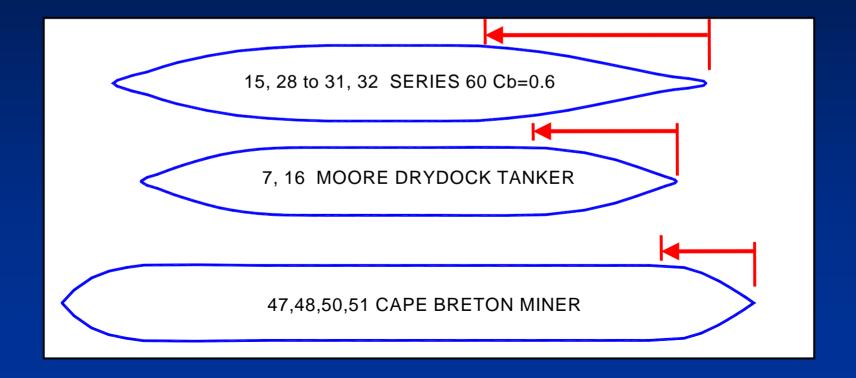
- Data for a given ship shows gH/V² increases with F_{*}
 - No waves measured for F_{*} below 0.1
 - Data shows quadratic or higher order relationship
- No simple mathematical function seems to ideally describe all data for all hulls
- Adopted quadratic expression for simplicity

$$\frac{gH}{V^2} = \beta \left(F_* - 0.1 \right)^2$$

β varies with hull form

Coefficient β seems to vary with Entrance Length, Le

- Defined as length from bow to start of parallel middle-body
- Importance for ship waves noted by Saunders (1957)
- Used in other predictive models (Gates and Herbich, 1975)

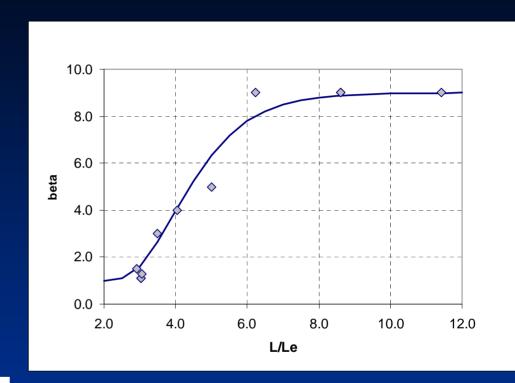


Variation of β with Hull Form

β correlated to entrance length

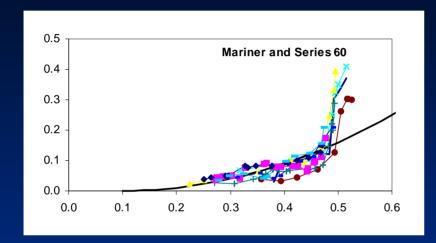
- Best correlation was based on L/Le ratio
 - Streamlined ships have β of 1 to 2
 - Blunt hulls have
 β up to 9
- Tentative relationship:

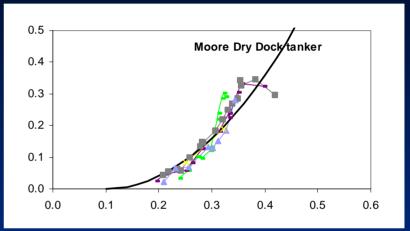
$$\beta = 1 + 8 * \tanh^3 \left(0.45 \left(\frac{L}{L_e} - 2 \right) \right)$$

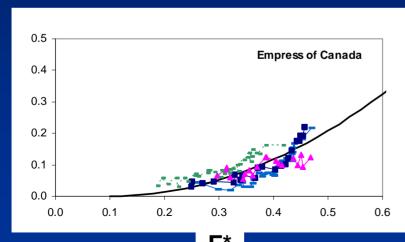


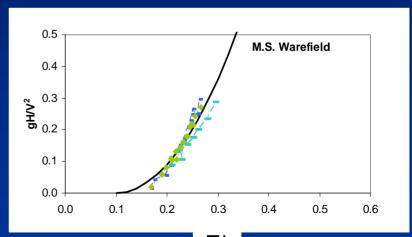
Results for gH/V² (at y/L=1) Measured and Predicted

$$\frac{gH}{V^2} = \beta (F_* - 0.1)^2$$



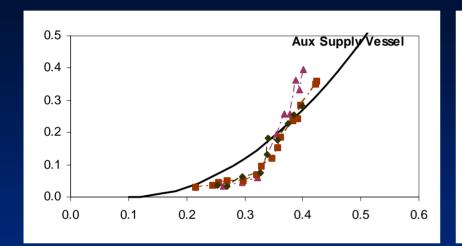


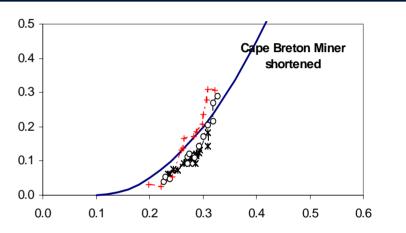


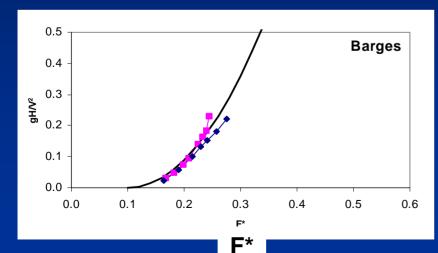


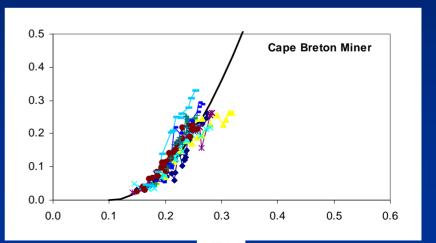
Results for gH/V² (at y/L=1) Measured and Predicted

$$\frac{gH}{V^2} = \beta (F_* - 0.1)^2$$







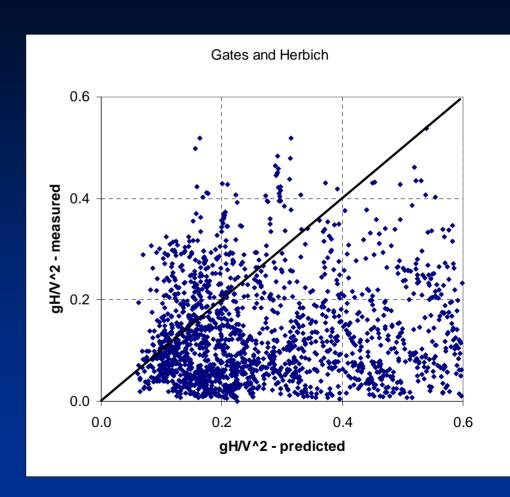


Gates & Herbich (1975)

Can be re-written in the

$$\frac{gH}{V^2} = k_w \frac{B}{L_e} F_L^{2/3} \left(\frac{y}{L}\right)^{-1/3}$$

- Critical problems:
 - Not dependent on depth-to-draft ratio (d/T)
 - Data shows exponent on F_L should be >1



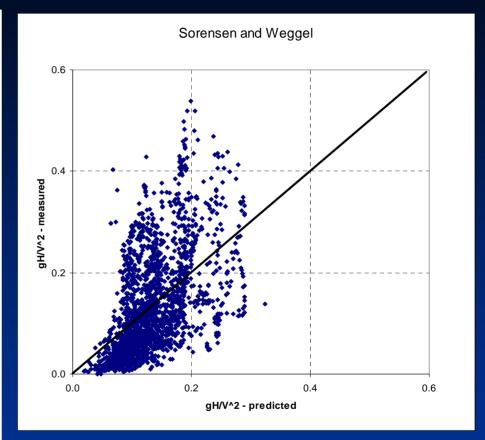
· Sorensen & Weggel (1984) and Weggel & Sorensen (1986)

$$H^* = \alpha (Y^*)^n$$
 where
$$\log \alpha = a + b \log d^* + c (\log d^*)^2$$
 with
$$a = -0.6 F_d^{-1} \quad b = 0.75 F_d^{-0.125} \quad c = 2.653 F_d - 1.95$$
 and
$$n = \beta (d^*)^\delta$$
 with
$$\beta = -0.225 F_d^{-0.699} \quad \text{for} \quad 0.2 < F_d < 0.55$$

$$= -0.342 \qquad \text{for} \quad 0.5 < F_d < 0.80$$

$$\delta = -0.118 F_d^{-0.356} \quad \text{for} \quad 0.2 < F_d < 0.55$$

$$= -0.146 \qquad \text{for} \quad 0.5 < F_d < 0.80$$
 and
$$H^* = \frac{H}{\nabla^{0.33}} \quad Y^* = \frac{Y}{\nabla^{0.33}} \quad d^* = \frac{d}{\nabla^{0.33}}$$



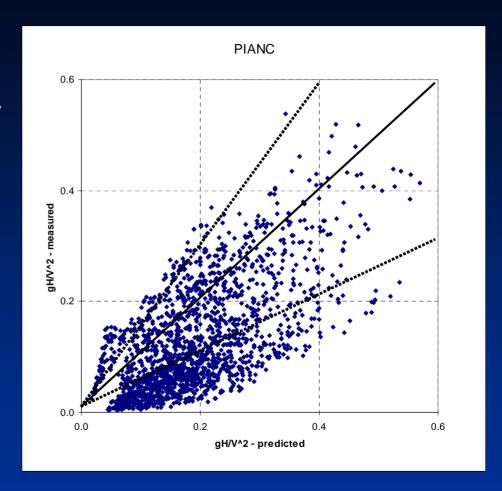
- A little complicated and removed from the physics
- Not dependent on hull form

• PIANC (1987)

 Based on work at Delft by Blaauw et al (1984) and others for ships in canals

$$\frac{gH}{V^2} = F_d^2 \left(\frac{y - B/2}{d}\right)^{-1/3}$$

- Similar functional form to proposed model but with F_d
- Tends to over-predict



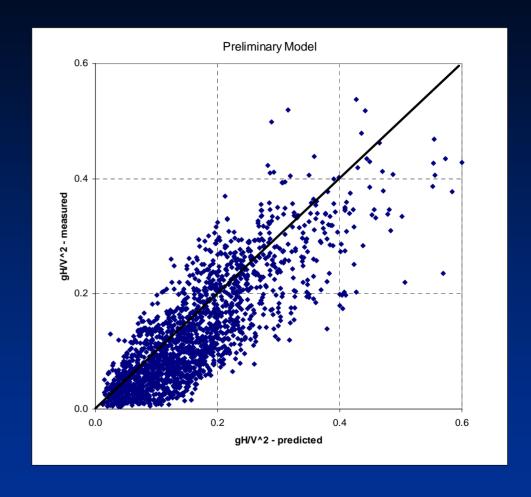
Proposed Model

Gives best agreement of the models evaluated based on 1200+ data points

$$\frac{gH}{V^2} = \beta \left(F_* - 0.1 \right)^2 \left(\frac{y}{L} \right)^{-1/3}$$
where
$$F_* = F_L \exp \left(\alpha \frac{T}{d} \right)$$

$$\alpha = 2.5 (1 - C_b)$$

$$\beta = 1 + 8 \tanh^3 \left(0.45 \left(\frac{L}{Le} - 2 \right) \right)$$



Summary and Conclusions Ship-Generated waves

- New model gives improved predictions
 - $exp(\alpha T/d)$ term "unifies" data
- Model can be further improved
 - $(y/L)^{-1/3}$ can be optimized
 - (F_{*}-0.1)² can be optimized

$$\frac{gH}{V^2} = \beta \left(F_* - 0.1 \right)^2 \left(\frac{y}{L} \right)^{-1/3}$$

where

$$F_* = F_L \exp\left(\alpha \frac{T}{d}\right)$$

$$\alpha = 2.35(1 - C_b)$$

$$\beta = 1 + 8 \tanh^3 \left(0.45 \left(\frac{L}{Le} - 2 \right) \right)$$

- Need more data in shallow water
 - Lab data for very shallow water T/d <1.3
 - Field data
- Try F* approach on Fast Ferries

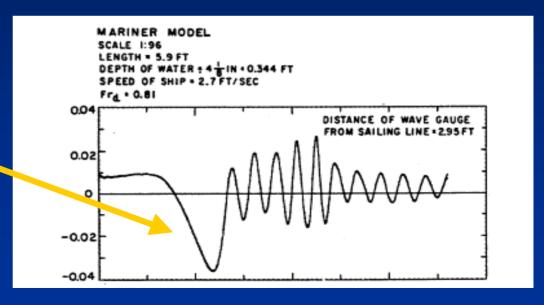
Other Recent Work on Vessel Effects

- Physical Model Study of Vessel Squat in Shallow Water:
 - Lab tests in Naval Academy towing tank
 - Measured drawdown and ship-generated waves
 - Measured ship squat and trim

Developed empirical equations based on F*

concept

Drawdown is local depression of water surface near hull in shallow water



Test Conditions

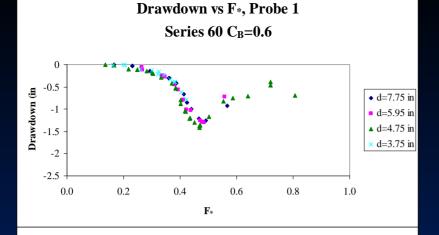


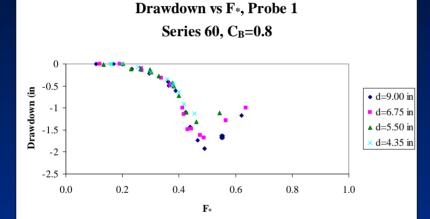
Series 60 Generic Commercial Hull $C_B = 0.80$ and $C_B = 0.60$

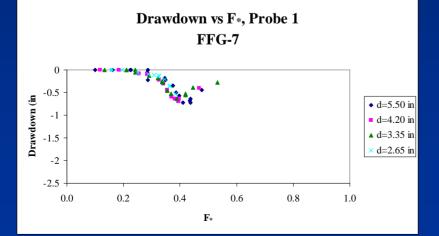


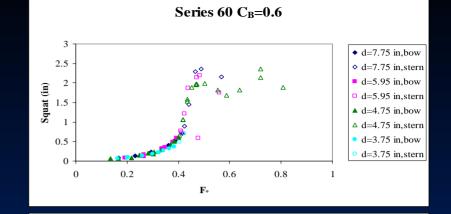
FFG-7 Class Frigate $C_B = 0.44$

Shallow water with d/T from 1.15 to 3

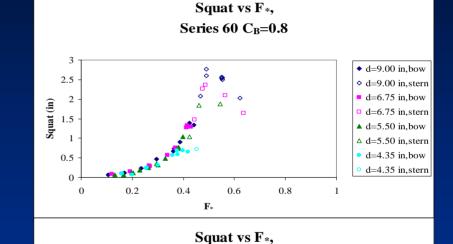


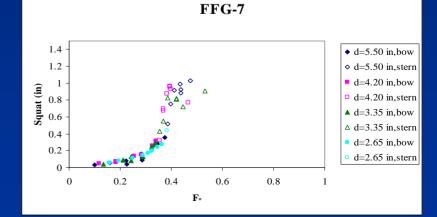


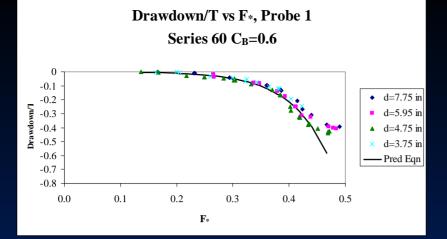


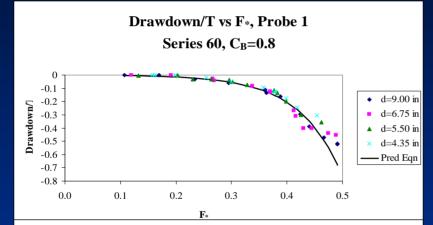


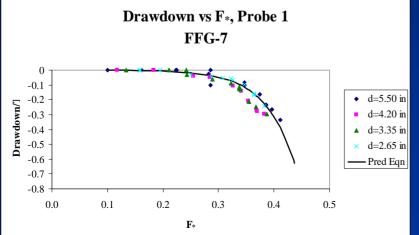
Squat vs F*,









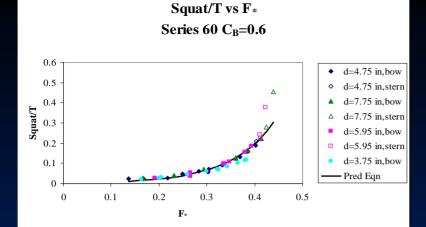


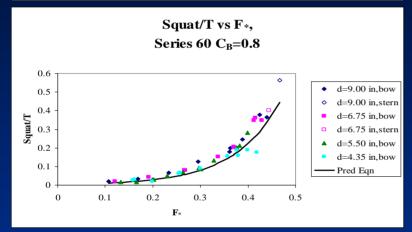
Drawdown Subcritical Conditions

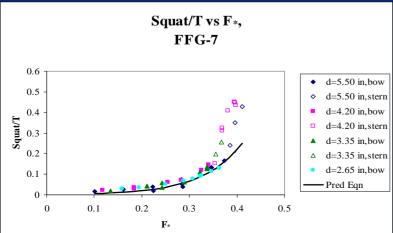
$$\frac{Drawdown}{T} = C_1 \exp(C_2 F_*)$$

$$C_1 = 0.0026 C_B - 0.001$$

$$C_1 = 0.0026C_B - 0.001$$
$$C_2 = -215.8\frac{T}{L} + 26.4$$







Ship Squat

Subcritical Conditions

$$\frac{S}{T} = C_3 \exp(C_4 F_*)$$

$$C_3 = 0.005C_B - 0.0004$$

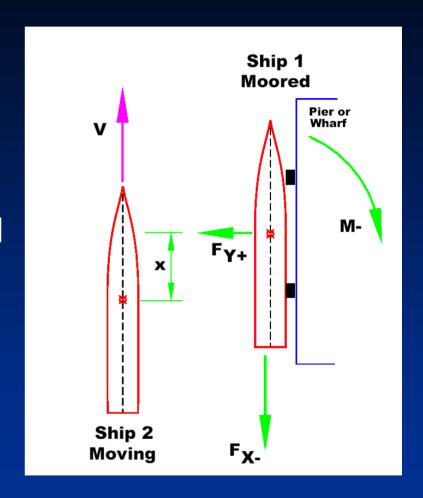
$$C_4 = -61.46 \frac{T}{L} + 14.10$$

Results compared favorably to other formulas for predicting ship squat:

ICORELS, Huuska/Guliev, and Millward

Other Recent Work on Vessel Effects

- Mooring Loads from Passing Vessels:
 - Lab tests started at Naval
 Academy in August 2003
 - Measure loads on moored vessel caused by passing vessel
 - Develop database for NAVFAC to evaluate and validate numerical codes



Passing Vessel Tests









